

## Review Form 1.6

Journal Name:	<a href="#">Journal of Engineering Research and Reports</a>
Manuscript Number:	Ms_JERR_81018
Title of the Manuscript:	Flexible Joint Robotic Manipulator Performance Improvement Using Mixed Synthesis Technique
Type of the Article	

### General guideline for Peer Review process:

This journal's peer review policy states that **NO** manuscript should be rejected only on the basis of '**lack of Novelty**', provided the manuscript is scientifically robust and technically sound. To know the complete guideline for Peer Review process, reviewers are requested to visit this link:

(<https://www.journaljerr.com/index.php/JERR/editorial-policy> )

### PART 1: Review Comments

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
<b>Compulsory</b> REVISION comments	<ol style="list-style-type: none"><li>1. Some more explanation is required in explaining the methodology given in the research paper.</li><li>2. Methology used in the research paper should be given in the form of flowchart also.</li><li>3. Along with the graphs, results should also be given and discussed in tabular form.</li></ol>	
<b>Minor</b> REVISION comments	There should be some more discussion in the graphs having results.	
<b>Optional/General</b> comments	----NA-----	

### PART 2:

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
Are there ethical issues in this manuscript?	(If yes, Kindly please write down the ethical issues here in details)	

### Reviewer Details:

Name:	<b>Neha Khurana</b>
Department, University & Country	<b>Mararishi Dayanand University, India</b>