An improvement in Estimating Finite Population Mean in the Presence of Outliers using Auxiliary Variable

ABSTRACT

In this study, generalized estimators were proposed for estimating the finite population mean when information on the minimum and maximum values of the auxiliary variable is known. The expression for the mean square errors and biases were derived to the first order of approximation. The performance of the proposed estimators, relative to conventional methods, has been rigorously analyzed, revealing notable improvements. Theoretical analysis confirms that correcting the estimators for mitigating maximum and minimum values by enhances it efficiency, and these findings have been empirically validated through comprehensive numerical analysis.

Keywords: Generalized estimator, Auxiliary Variable, Outliers, Mean Square Error.

1. Introductions

The estimation of the population parameters such as mean, total, proportion and even population ratio of the study variable, with greater precision, minimum cost and time is a persistent issue in sampling practice. The use of an auxiliary information can increase the precision of an estimator when study variable, say, y is highly correlated with auxiliary variable, say, x. For example, oil production and revenue, exchange rate and inflation rate, agricultural output and subsidies, government expenditure and gross domestic growth, malaria incidence and mosquito net distribution, infant mortality rate and immunization coverage patient age and blood pressure levels, body mass index and cholesterol levels. Cochran (1940), used auxiliary information to develop the ratio estimator for estimating population mean of the study variable using single phase sampling design. Several studies among many exist on the use of auxiliary variables in enhancing the precision of the study variable in sample survey, such as: Samiuddin and Hanif (2007), Singh and Espejo (2007), Hanif *el tal.* (2010), Swain (2012), Shahbaz *et al* (2014), Kanwai *et al.* (2016). Though, the prior detection of the presence of extreme value in the data set on both the study and auxiliary variables, to the application of estimators, is very germane to obtaining efficient estimate. Ratio, regression, difference, product and mixed estimators are also affected by the presence of extreme value in the data set which produce less efficient estimate. Some of the studies of extreme values correction include the following: Khan & Shabbir (2013) suggested some modified ratio, product, and regression type estimators when using minimum and maximum values. Al-Hossain and Khan (2014) worked on the estimation of population mean using maximum and minimum values under simple random sampling by incorporating the knowledge of two auxiliary variables. Khan (2015), presents a ratio estimator for the estimation of finite population mean of the study variable under double sampling scheme when there are unusually low and unusually high values and analyzes their properties. Daraz *et al.* (2018), suggested an improved class of ratio type estimators in estimating the finite population mean when information on minimum and maximum values of the auxiliary variable is known. Other authors that worked on the correction of extreme values comprises: Mohanty and Sahoo (1995), Walia *et al.* (2015), Cekim and Cingi (2016) and Olayiwola *et al.*, (2021**).** In their studies the proposed estimators are relative to their usual counterparts.

In this study, a generalized modified ratio-product-cum-exponential estimator that can handle the ratio, product and regression challenges for outliers in order to improve the validity of the population parameters is proposed.

2. Materials and methods

2.1 Research Design

Consider a finite population $U=(U_1,U_2,---,U_N)$ of size N units. Let y and x denote the study variable and auxiliary variable respectively. A sample of size n $(n<N)$ assuming a simple random sampling without replacement (SRSWOR) s of size n $(n<N)$ is drawn from the population U $(s\subset U)$. The purpose is to estimate the population mean of the study variable $\bar{Y}=\frac{1}{N}\sum y_i$. It is further assumed that the population mean $\bar{X}=\frac{1}{N}\sum x_i$ of the auxiliary variable x is known. The minimum says (x_{min}) and maximum say (x_{max}) values of the auxiliary variables are also assumed to be known.

Mean per unit estimator for finite population mean is very sensitive to unexpected values, if there exists unexpected very large (say y_{max}) and very small (say y_{min}) units in the population. The mean per unit estimator is very sensitive to these unusual observations and as a result population mean will be either underestimated (in case the sample contains $y$min) or overestimated (in case it containsy_{max}). To overcome this situation Sarndal (1972) suggested the following unbiased estimator:

$$\bar{y}_s=\begin{cases}(\bar{y}+c_1),\\(\bar{y}-c_1),\\\bar{y}\end{cases} \tag{1}$$

where,

$(\bar{y}+c_1)$ if sample contains y_{min} but not y_{max}

$(\bar{y}-c_1)$ if sample contains y_{max} but not y_{min},

$\bar{y}$ for all other samples, and c is a constant.

The variance of $\bar{y}_s$ is given by:

$$V(\bar{y}_s)=\theta S_y^2-\frac{2\theta nc}{N-1}(y_{max}-y_{min}-nc) \tag{2}$$

Where: $= \frac{1}{n} - \frac{1}{N}$, $S_y^2 = \frac{1}{1-N} \sum_{i=1}^{N} (y_i - \bar{Y})^2$

2.1 Estimators for Estimating the Population Mean

Some of the estimators for estimating the population mean includes:

$$V(\bar{y}_s)_{opt} = V(\bar{y}) \; - \frac{\theta(\Delta y)^2}{2(N-1)} \tag{3}$$

which is always smaller than $V(\bar{y})$

Where:

$V(\bar{y})$ is the variance of mean per unit estimator $\bar{y} = \sum_{i=1}^{n} \frac{y_i}{n}$ is given by $V(\bar{y}) = \theta S_y^2$

The sample mean of the study variable is given as:

$$\bar{y} = \frac{1}{n} \sum_{i=1}^{n} y_i \tag{4}$$

which is an unbiased estimator of finite population variance $\left(S_y^2\right)$and its variance is

$$\text{Var.}(\bar{y}) = \theta \bar{Y}^2 C_y^2 \tag{5}$$

$$\text{Bias}(\bar{y}) = 0 \tag{6}$$

Cochran (1940) ratio estimator

$$\bar{y}_R = \bar{y} \frac{\bar{X}}{\bar{x}} \tag{7}$$

$$\text{MSE}(\bar{y}_R) = \theta \bar{Y}^2 (C_y^2 + C_x^2 - 2\rho_{yx} C_y C_x) \tag{8}$$

$$\text{Bias}(\bar{y}_R) = \theta \bar{Y} (C_x^2 - \rho_{yx} C_y C_x) \tag{9}$$

Murthy (1964) product estimator

$$t_P = \bar{y} \frac{\bar{x}}{\bar{X}} \tag{10}$$

$$\text{MSE}(\bar{y}_p) = \theta \bar{Y}^2 (C_y^2 + C_x^2 + 2\rho_{yx} C_y C_x) \tag{11}$$

$$\text{Bias}(\bar{y}_P) = \theta \bar{Y} \rho_{yx} C_y C_x \tag{12}$$

Cochran (1942) regression estimator

$$\bar{y}_{Reg.} = \bar{y} + b_{yx}(\bar{X} - \bar{x}) \tag{13}$$

$$\text{MSE}\ (\bar{y}_{Reg.}) = \theta \bar{Y}^2 C_y^2 \left(1 - \rho_{yx}^2\right) \tag{14}$$

Bahl and Tuteja (1991), exponential ratio and product type estimator

$$\bar{y}_{ER} = \bar{y}\ exp\left[\frac{\bar{X} - \bar{x}}{\bar{X} + \bar{x}}\right] \tag{15}$$

$$\text{MSE}(\bar{y}_{ER}) = \bar{Y}^2\theta\left[C_y^2 + \frac{1}{4}C_x^2 - \rho_{yx}C_yC_x\right] \tag{16}$$

$$\text{Bias}\ (\bar{y}_{ER}) = \theta\bar{Y}\left[\frac{3C_x^2}{8} - \frac{\rho_{yx}C_yC_x}{2}\right] \tag{17}$$

$$\bar{y}_{EP} = \bar{y}\ exp\left[\frac{\bar{x} - \bar{X}}{\bar{x} + \bar{X}}\right] \tag{18}$$

$$\text{MSE}\ (\bar{y}_{EP}) = \theta\bar{Y}^2\left[C_y^2 + \frac{1}{4}C_x^2 + \rho_{yx}C_yC_x\right] \tag{19}$$

$$\text{Bias}\ (\bar{y}_{EP}) = \theta\bar{Y}\left[\frac{\rho_{yx}C_yC_x}{2} - \frac{C_y^2}{8}\right] \tag{20}$$

2.3 Proposed Estimators

Here, the mixed optimum,T_{GC1} and mixed non-optimum T_{GC2} estimators are modified to handle the case of extreme values on both the study and auxiliary variables.

$$T_{GC1} = 2^{-1}\bar{y}_{c_0}\left\{\left(\frac{\bar{X}}{\bar{x}_{c_1}}\right)^{\alpha_2} + \left(\frac{\bar{x}_{c_1}}{\bar{X}}\right)^{1-\alpha_2}\right\}\left\{exp\left[\frac{\bar{X} - \bar{x}_{c_1}}{\bar{X} + \bar{x}_{c_1}}\right]\right\} \tag{21}$$

$$T_{GC1} = \begin{cases} 2^{-1}(\bar{y} + c_0)\left\{\left(\frac{\bar{X}}{\bar{x} + c_1}\right)^{\alpha_2} + \left(\frac{\bar{x} + c_1}{\bar{X}}\right)^{1-\alpha_2}\right\}\left\{exp\left[\frac{\bar{X} - (\bar{x} + c_1)}{\bar{X} + (\bar{x} + c_1)}\right]\right\} \\ 2^{-1}(\bar{y} - c_0)\left\{\left(\frac{\bar{X}}{\bar{x} - c_1}\right)^{\alpha_2} + \left(\frac{\bar{x} - c_1}{\bar{X}}\right)^{1-\alpha_2}\right\}\left\{exp\left[\frac{\bar{X} - (\bar{x} - c_1)}{\bar{X} + (\bar{x} - c_1)}\right]\right\} \\ 2^{-1}\bar{y}\left\{\left(\frac{\bar{X}}{\bar{x}}\right)^{\alpha_2} + \left(\frac{\bar{x}}{\bar{X}}\right)^{1-\alpha_2}\right\}\left\{exp\left[\frac{\bar{X} - \bar{x}}{\bar{X} + \bar{x}}\right]\right\} \end{cases} \tag{22}$$

$$T_{GC2} = 2^{-1}\bar{y}_{c_0}\left\{\left(\frac{\bar{X}}{\bar{x}_{c_1}}\right) + \left(\frac{\bar{x}_{c_1}}{\bar{X}}\right)\right\}\left\{exp\left[\frac{\bar{X} - \bar{x}_{c_1}}{\bar{X} + \bar{x}_{c_1}}\right]\right\} \tag{23}$$

$$T_{GC2} = \begin{cases} 2^{-1}(\bar{y}+c_0)\left\{\left(\frac{\bar{X}}{\bar{x}+c_1}\right)+\left(\frac{\bar{x}+c_1}{\bar{X}}\right)\right\}\left\{exp\left[\frac{\bar{X}-(\bar{x}+c_1)}{\bar{X}+(\bar{x}+c_{1)}}\right]\right\} \\ 2^{-1}(\bar{y}-c_0)\left\{\left(\frac{\bar{X}}{\bar{x}-c_1}\right)+\left(\frac{\bar{x}-c_1}{\bar{X}}\right)\right\}\left\{exp\left[\frac{\bar{X}-(\bar{x}-c_1)}{\bar{X}+(\bar{x}-c_{1)}}\right]\right\} \\ 2^{-1}\bar{y}\left\{\left(\frac{\bar{X}}{\bar{x}}\right)+\left(\frac{\bar{x}}{\bar{X}}\right)\right\}\left\{exp\left[\frac{\bar{X}-\bar{x}}{\bar{X}+\bar{x}}\right]\right\} \end{cases} \quad (24)$$

To obtain the bias and the MSE for T_{GC1} and T_{GC2}, we define the following relative error terms.

$$\bar{y}_{co} = \bar{Y}(1+\bar{e}_o) \; and \; \bar{x}_{c1} = \bar{X}(1+\bar{e}_1) \quad (25)$$

$$E(\bar{e}_o) = E(\bar{e}_1) = 0, \; E(e_0^2) = \frac{\theta}{\bar{Y}^2}\left(S_y^2 - \frac{2nc_0}{N-1}(y_{max} - y_{min} - nc_0)\right),$$

$$E(e_1^2) = \frac{\theta}{\bar{X}^2}\left(S_x^2 - \frac{2nc_1}{N-1}(x_{max} - x_{min} - nc_1)\right), \text{ and}$$

$$E(e_0e_1) = \frac{\theta}{\bar{Y}\bar{X}}\left(S_{yx}^2 - \frac{n}{N-1}(c_1(y_{max} - y_{min}) + c_0(x_{max} - x_{min}) - 2nc_0c_1)\right) \quad (26)$$

Applying (25) in (26) gave (27)

$$T_{p1} = \left[\bar{Y} + \bar{Y}\bar{e}_0 - \alpha_2\bar{Y}\bar{e}_1 - \alpha_2\bar{Y}\,\bar{e}_0\,\bar{e}_1 + \frac{1}{2}\left(\frac{1}{4} + \alpha_2 + \alpha_2^2\right)\bar{Y}\bar{e}_1^2\right] \quad (27)$$

Subtracting $\bar{Y}$ from both sides of (27) and taking expectation of both sides, we get the bias of the estimator T_{GC1}

$$\text{Bias}(T_{GC1}) = E(T_{GC1} - \bar{Y}) = E\left[\bar{Y}\bar{e}_0 - \alpha_2\bar{Y}\bar{e}_1 - \alpha_2\bar{Y}\,\bar{e}_0\,\bar{e}_1 + \frac{1}{2}\left(\frac{1}{4} + \alpha_2 + \alpha_2^2\right)\bar{Y}\bar{e}_1^2\right] \quad (28)$$

Applying (26) in (25), we obtain the bias of T_{GC1}

$$\text{Bias}(T_{GC1}) = \bar{Y}\left[\frac{1}{2}\left(\frac{1}{4} + \alpha_2 + \alpha_2^2\right)\frac{\theta}{\bar{X}^2}\left\{S_x^2 - \frac{2nC_1}{N-1}(\Delta x - nC_1)\right\} - \alpha_2\frac{\theta}{\bar{Y}\bar{X}}\left\{S_{yx} - \frac{n}{N-1}(C_1\Delta y + C_0\Delta x) - 2nC_0C_1\right\}\right] \quad (29)$$

$$\text{Bias}(T_{GC1}) = \bar{Y}\left[\frac{1}{2}\left(\frac{1}{4} + \alpha_2 + \alpha_2^2\right)\frac{\theta R^2}{\bar{Y}^2}\left\{S_x^2 - \frac{2nC_1}{N-1}(\Delta x - nC_1)\right\} - \alpha_2\frac{\theta R}{\bar{Y}^2}\left\{S_{yx} - \frac{n}{N-1}(C_1\Delta y + C_0\Delta x) - 2nC_0C_1\right\}\right] \quad (30)$$

$$\text{Bias}(T_{GC1}) = \frac{\theta R}{\bar{Y}}\left[\frac{1}{2}R\left(\frac{1}{4}+\alpha_2+\alpha_2^2\right)\left\{S_x^2-\frac{2nC_1}{N-1}(\Delta x-nC_1)\right\}-\alpha_2\left\{S_{yx}-\frac{n}{N-1}(\Delta yC_1+\Delta xC_0)-2nC_0C_1\right\}\right] \quad (31)$$

To obtain the MSE of T_{GC1}, we subtract $\bar{Y}$ from both sides of (27), retaining terms in first degree of $e's$, squaring both sides and then taking expectations of both sides, we have:

$$\text{MSE}(T_{GC1}) = E\left(T_{p1ex}-\bar{Y}\right)^2 = \bar{Y}^2E[\bar{e}_0-\alpha_2\bar{e}_1]^2 \quad (32)$$

$$MSE(T_{GC1}) = \bar{Y}^2E[\bar{e}_0^2+\ \alpha_2^2\bar{e}_1^2-2\alpha_2\bar{e}_0\ \bar{e}_1] \quad (33)$$

Substituting equation (26) in (33) will give:

$$MSE(T_{GC1}) = \bar{Y}^2\left[\frac{\theta}{\bar{Y}^2}\left\{S_y^2-\frac{2nC_0}{N-1}(\Delta y-nC_0)\right\}+\frac{\alpha_2^2\theta}{\bar{X}^2}\left\{S_x^2-\frac{2nC_1}{N-1}(\Delta x-nC_1)\right\}-\frac{2\alpha_2\theta}{\bar{Y}\bar{X}}\left\{S_{yx}-\frac{n}{N-1}(\Delta yC_1+\Delta xC_0)-2nC_0C_1\right\}\right] \quad (34)$$

$$MSE(T_{GC1}) = \theta\left[\left(S_y^2\ +\alpha_2^2R^2S_x^2-2\alpha_2RS_{yx}\right)-\frac{2nC_0\Delta y}{N-1}+\frac{2n\alpha_2RC_1\Delta y}{N-1}+\frac{2n^2C_0^2}{N-1}+\frac{2n\alpha_2RC_0\Delta x}{N-1}-\frac{2n\alpha_2^2R^2C_1\Delta x}{N-1}+\frac{2n^2\alpha_2^2R^2C_1^2}{N-1}-\frac{4n^2\alpha_2RC_0\ C_1}{N-1}\right] \quad (35)$$

$$MSE(T_{GC1}) = \theta\left[\left(S_y^2\ +\alpha_2^2R^2S_x^2-2\alpha_2RS_{yx}\right)-\frac{2n}{N-1}(C_0-\alpha_2RC_1)\{\Delta y-\alpha_2R\Delta x-n(C_0-\alpha_2RC_1)\}\right] \quad (36)$$

To obtain the optimum value of C_0 and C_1 we perform partial differential equation of (36) w.r.t C_0 and C_1 and equate each to zero

$$C_0-\alpha_2RC_1 = \frac{\Delta y-\alpha_2R\Delta x}{2n} \quad (37)$$

Also,

$$C_0-\alpha_2RC_1 = \frac{\Delta y-\alpha_2R\Delta x}{2n} \quad (38)$$

In the attempt to perform partial differentiation on the MSE of T_{GC1} with respect to C_0 and C_1,we have one equation with two unknowns so unique, solution is not possible, therefore,

$$C_{0(opt)} = \frac{y_{max}-y_{min}}{2n} = \frac{\Delta y}{2n} \tag{39}$$

$$C_{1(opt)} = \frac{x_{max}-x_{min}}{2n} = \frac{\Delta x}{2n} \tag{40}$$

Substitute (39) and (40) into (36), and simplify we obtain

$$MSE(T_{GC1})_{opt} = \theta\Bigg[\left(S_y^2 + \alpha_2^2 R^2 S_x^2 - 2\alpha_2 R S_{yx}\right) - \frac{2n}{N-1}\left(\frac{\Delta y}{2n} - \alpha_2 R\frac{\Delta x}{2n}\right)\left\{\Delta y - \alpha_2 R\Delta x - n\left(\frac{\Delta y}{2n} - \alpha_2 R\frac{\Delta x}{2n}\right)\right\}\Bigg] \tag{41}$$

$$MSE(T_{GC1})_{opt} = \theta\left[\left(S_y^2 + \alpha_2^2 R^2 S_x^2 - 2\alpha_2 R S_{yx}\right) - \left\{\frac{(\Delta y - \alpha_2 R\Delta x)^2}{2(N-1)}\right\}\right] \tag{42}$$

Special cases of the proposed estimator T_{GC1}

From (42) we try to investigate different common scenarios for the value of α_2

Case (I): $\alpha_2 = -1$,

$$MSE(\bar{y}_{PC})_{opt} = \left[\theta\bar{Y}^2\{C_y^2 + C_x^2 + 2C_y C_x \rho_{yx}\} - \theta\left\{\frac{(\Delta y + R\Delta x)^2}{2(N-1)}\right\}\right] \tag{43}$$

$$MSE(\bar{y}_{PC})_{opt} = \left[\mathrm{MSE}(\bar{y}_P) - \left\{\frac{\theta(\Delta y + \Delta x)^2}{2R(N-1)}\right\}\right] \tag{44}$$

Therefore, (44) can be used when the correlation between the study variable and auxiliary variable is less than zero.

Case (II): $\alpha_2 = 0$

$$V(\bar{y}_s) = \theta\left[\bar{Y}^2 C_y^2 - \left\{\frac{(\Delta y)^2}{2(N-1)}\right\}\right] \tag{45}$$

Also, (45) is appropriate when the correlation between the auxiliary variable and study variable is zero

$$V(\bar{y}_s) = \left[V(\bar{y}) - \left\{\frac{\theta(\Delta y)^2}{2(N-1)}\right\}\right] \tag{46}$$

Case (III): $\alpha_2 = 1$,

$$MSE(\bar{y}_{RC}) = \left[\theta\bar{Y}^2\{C_y^2 + C_x^2 - 2C_yC_x\rho_{yx}\} - \theta\left\{\frac{(\Delta y - R\Delta x)^2}{2(N-1)}\right\}\right] \tag{47}$$

More so,(47) is applicable when the correlation between the study variable and auxiliary variable is greater than zero

$$MSE(\bar{y}_{RC}) = \left[\text{MSE}(\bar{y}_R) - \theta\left\{\frac{(\Delta y - R\Delta x)^2}{2(N-1)}\right\}\right] \tag{48}$$

Case (Iv): $\alpha_2 = \frac{C_y\rho_{yx}}{C_x}$

$$MSE(Reg.) = \left[\theta\{\bar{Y}^2C_y^2 + \bar{Y}^2C_y^2\rho_{yx}^2 - 2\bar{Y}^2C_y^2\rho_{yx}^2\} - \theta\left\{\frac{(\Delta y - \beta\Delta x)^2}{2(N-1)}\right\}\right] \tag{49}$$

where: $\beta = \frac{s_y\rho_{yx}}{S_x}$

$$MSE\left(\bar{y}_{Reg.}\right) = \left[\bar{Y}^2C_y^2(1-\rho_{yx}^2) - \theta\left\{\frac{(\Delta y - \beta\Delta x)^2}{2(N-1)}\right\}\right] \tag{50}$$

$$MSE(Reg.) = \left[V\left(\bar{y}_{LR}\right) - \theta\left\{\frac{(\Delta y - \beta\Delta x)^2}{2(N-1)}\right\}\right] \tag{51}$$

Lastly, (51) is applicable when the correlation between the variables is linear and negative or positive, and the line did not pass through the origin.

Similarly, applying (25) in (23) we obtained

$$T_{p2} = \left[\bar{Y} + \bar{Y}\bar{e}_0 - \frac{1}{2}\bar{Y}\bar{e}_1 - \frac{1}{2}\bar{Y}\bar{e}_0\,\bar{e}_1 + \frac{7}{8}\bar{Y}\,\bar{e}_1^2\right] \tag{52}$$

Subtracting $\bar{Y}$ from both sides of (52) and taking expectation of both sides, we get the bias of the estimator T_{GC2}

$$\text{Bias}(T_{GC2}) = E(t_{p2} - Y) = E\left[\bar{Y}\bar{e}_0 - \frac{1}{2}\bar{Y}\bar{e}_1 - \frac{1}{2}\bar{Y}\bar{e}_0\,\bar{e}_1 + \frac{7}{8}\bar{Y}\,\bar{e}_1^2\right] \tag{53}$$

Applying (26) in (53), we obtained the bias of T_{GC1}

$$\text{Bias}(T_{GC2}) = \bar{Y}\left[\frac{7\theta}{8\bar{X}^2}\left\{S_x^2 - \frac{2nC_1}{N-1}(\Delta x - nC_1)\right\} - \frac{\theta}{2\bar{Y}\bar{X}}\left\{S_{yx} - \frac{n}{N-1}(\Delta yC_1 + \Delta xC_0) - 2nC_0C_1\right\}\right] \tag{54}$$

$$\text{Bias}(T_{GC2}) = \frac{\theta}{\bar{X}}\left[\frac{7\bar{Y}}{8\bar{X}}\bar{X}^2C_x^2 - \frac{1}{2}\bar{Y}C_x\bar{X}\,C_y\rho_{yx} + \frac{n}{2(N-1)}\left\{\frac{nC_0\Delta x}{2(N-1)} - \frac{14n\bar{Y}C_1\Delta x}{8\bar{X}(N-1)} - \frac{2n^2C_0C_1}{2(N-1)} + \frac{14n^2\bar{Y}C_1^2}{8\bar{X}(N-1)} + \frac{n\Delta yC_1}{2(N-1)}\right\}\right] \quad (55)$$

$$\text{Bias}(T_{GC2}) = \left[\bar{Y}\left(\frac{7}{8}\theta C_x^2 - \frac{1}{2}C_yC_x\,\rho_{yx}\right) + \frac{n\theta}{2\bar{X}(N-1)}\left\{\left(C_0 - \frac{7\bar{Y}C_1}{2\bar{X}}\right)\Delta x - \left(2C_0 + \frac{7\bar{Y}nC_1}{2\bar{X}}\right)nC_1 + C_1\Delta y\right\}\right] \quad (56)$$

To obtain the MSE of T_{GC2}, we subtract $\bar{Y}$ from both sides of (52),retaining terms in first degree of $e's$, squaring both sides and then taking expectations of both sides, we have:

$$T_{GC2} = \left[\bar{Y} + \bar{Y}\bar{e}_0 - \frac{1}{2}\bar{Y}\,\bar{e}_1 - \frac{1}{2}\bar{Y}\bar{e}_0\,\bar{e}_1 + \frac{7}{8}\bar{Y}\,\bar{e}_1^2\right] \quad (57)$$

$$\text{MSE}(T_{GC2}) = E\left(t_{p2} - \bar{Y}\right)^2 = E\left[\bar{Y}\bar{e}_0 - \frac{1}{2}\bar{Y}\bar{e}_1\right]^2 \quad (58)$$

$$MSE(T_{GC2}) = \bar{Y}^2E\left[\bar{e}_0^2 + \frac{1}{4}\bar{e}_1^2 - \frac{1}{2}(2\bar{e}_0\bar{e}_1)\right] \quad (59)$$

Let $\frac{1}{2} = a$

$$MSE(T_{GC2}) = \bar{Y}^2E[\bar{e}_0^2 + a^2\bar{e}_1^2 - 2a\bar{e}_0\bar{e}_1] \quad (60)$$

$$MSE(T_{GC2}) = \bar{Y}^2E\left[\frac{\theta}{\bar{Y}^2}\left\{S_y^2 - \frac{2nC_0}{N-1}(\Delta y - nC_0)\right\} + \frac{a^2\theta}{\bar{X}^2}\left\{S_x^2 - \frac{2nC_1}{N-1}(\Delta x - nC_1)\right\} - \frac{2a\theta}{\bar{Y}\bar{X}}\left\{S_{yx} - \frac{n}{N-1}(\Delta yC_1 + \Delta xC_0) - 2nC_0C_1\right\})\right] \quad (61)$$

$$MSE(T_{GC2}) = \theta\left[\left(S_y^2 + a^2R^2S_x^2 - 2aRS_{yx}\right) - \frac{2nC_0\Delta y}{N-1} + \frac{2naRC_1\Delta y}{N-1} + \frac{2naRC_0\Delta x}{N-1} - \frac{2na^2R^2C_1\Delta x}{N-1} + \frac{2n^2C_0^2}{N-1} + \frac{2n^2a^2R^2C_1^2}{N-1} - \frac{4n^2aRC_0\,C_1}{N-1}\right] \quad (62)$$

$$MSE(T_{GC2}) = \theta\left[\left(S_y^2 + a^2R^2S_x^2 - 2aRS_{yx}\right) - \frac{2n}{N-1}(C_0 - aRC_1)\{\Delta y - aR\Delta x - n(C_0 - aRC_1)\}\right] \quad (63)$$

but

$$C_{0(opt)} = \frac{y_{max} - y_{min}}{2n} = \frac{\Delta y}{2n} \tag{64}$$

$$C_{1(opt)} = \frac{x_{max} - x_{min}}{2n} = \frac{\Delta x}{2n} \tag{65}$$

Substitute (64) and (65) into (63) and simplify, we obtained

$$MSE(T_{p2ex}) = \theta\left[\{S_y^2 + a^2R^2S_x^2 - 2aRS_{yx}\} - \frac{2n}{N-1}\left(\frac{\Delta y}{2n} - aR\frac{\Delta x}{2n}\right)\left\{\Delta y - aR\Delta x - n\left(\frac{\Delta y}{2n} - \frac{aR\Delta x}{2n}\right)\right\}\right] \tag{66}$$

$$MSE(T_{GC2}) = \theta\left[\{S_y^2 + a^2R^2S_x^2 - 2aRS_{yx}\} - \left\{\frac{(\Delta y - aR\Delta x)^2}{2(N-1)}\right\}\right] \tag{67}$$

But $a = \frac{1}{2}$

$$MSE(T_{GC2}) = \theta\left[\bar{Y}^2\left\{C_y^2 + \frac{1}{4}C_x^2 - C_yC_x\rho_{yx}\right\} - \left\{\frac{(2\Delta y - R\Delta x)^2}{8(N-1)}\right\}\right] \tag{68}$$

$$MSE(T_{GC2}) = \left[MSE(T_{ERC}) - \theta\left\{\frac{(2\Delta y - R\Delta x)^2}{8(N-1)}\right\}\right] \tag{69}$$

The MSE of (69) has a correction factor of the ratio exponential estimator.

3. Results and discussion

3.1 Comparison of estimators

(1) Comparison with the generalized proposed (mixed optimum) estimator

(a) Comparison of proposed estimator T_{RC} type Estimator

(i) Mean Per Unit Estimator [(5) and (48)]

$V(\bar{y}) - M(T_{RC}) > 0$ or if

$$\rho_{yx} > \frac{1}{2}\left[\frac{RS_x}{S_y} - \frac{(\Delta y - R\Delta x)^2}{2RS_yS_x(N-1)}\right] \tag{70}$$

The corrected ratio estimator of (48) is more efficient than mean per unit estimator given in (5)

(ii) Usual ratio estimator [(8) and (48)]

$M(\bar{y}_R) - M(T_{RC}) > 0$ or if

$$\frac{(\Delta y - R\Delta x)^2}{2RS_yS_x(N-1)} > 0 \quad (71)$$

The corrected ratio estimator of (48) is more efficient than its contemporary ratio estimator of (8) .

(iii) Usual exponential ratio estimator [(16) and (48)]

$M(\bar{y}_{ER}) - M(T_{RC}) > 0$ or if

$$\rho_{yx} > -\frac{1}{2}\left[\frac{5RS_x}{2S_y} + \frac{(\Delta y - R\Delta x)^2}{RS_yS_x(N-1)}\right] \quad (72)$$

Estimator (48) is more efficient than estimator(16)

(b) Comparison of proposed estimator T_{PC} type Estimator

Also, we compare the efficiency of the corrected product estimator with it usual counterpart.

(i) Mean Per Unit Estimator [(5) and (44)

$V(\bar{y}) - M(T_{PC}) > 0$ or if

$$\rho_{yx} > \frac{1}{2}\left[\frac{RS_x}{S_y} - \frac{(\Delta y + R\Delta x)^2}{2RS_yS_x(N-1)}\right] \quad (73)$$

The corrected product estimator of (44) is more efficient than the mean per unit estimator.

(ii) Usual product estimator [(11) and (44)]

$M(\bar{y}_P) - M(T_{PC}) > 0$ or if

$$\frac{(\Delta y + R\Delta x)^2}{2RS_yS_x(N-1)} > 0 \quad (74)$$

Corrected product estimator of (44) is more efficient than it product counterpart of (11)

(iii) Usual exponential product estimator [(16) and (44)]

$M(\bar{y}_{EP}) - M(T_{PC}) > 0$ or if

$$\rho_{yx} > -\frac{1}{2}\left[\frac{5RS_x}{2S_y} + \frac{(\Delta y + R\Delta x)^2}{RS_yS_x(N-1)}\right] \quad (75)$$

The corrected exponential product estimator of(44) is more efficient than the usual product estimator of (16)

(c) Comparison of proposed estimator T_{Reg} type Estimator [(5) and (51)]

(i) Mean Per Unit Estimator

$V(\bar{y}) - V(\bar{y}_{lrc}) > 0$ or if

$$\rho_{yx}^2 > -\frac{(\Delta y - \beta\Delta x)^2}{2S_{yx}^2(N-1)} \quad (76)$$

From (74) it is obvious that the regression estimator of (51) is more efficient than the mean per unit estimator of (5)

(iv) Usual regression estimator [(14) and (51)]

$V(\bar{y}_{lr}) - V(\bar{y}_{lrc}) > 0$ or if

$$\frac{(\Delta y - \beta\Delta x)^2}{2RS_yS_x(N-1)} > 0 \quad (77)$$

It is showed that the corrected regression estimator of (51) is more efficient than the usual regression estimator of (14)

2. Comparison with the mixed non-optimum estimator

(a) comparison of proposed estimator T_{GC2}

(i) Mean Per Unit Estimator [(5) and (69)]

$V(\bar{y}) - M(T_{GC2}) > 0$ or if

$$\rho_{yx} > \frac{1}{4}\left[\frac{RS_x}{S_y} - \frac{(2\Delta y - R\Delta x)^2}{2RS_yS_x(N-1)}\right] \quad (78)$$

It is clear from (76) that corrected exponential ratio estimator is more efficient than the exponential ratio estimator.

(ii) Usual exponential ratio [(16) and (69)]

$M(\bar{y}_{ER}) - M(T_{GC2}) > 0$ or if

$$\frac{(2\Delta y - R\Delta x)^2}{8R(N-1)} > 0 \quad (79)$$

The corrected exponential ratio estimator of (69) is more efficient than the usual exponential ratio estimator of (16).

3.2 Numerical illustration

The Percent Relative Efficiency (PRE) is a statistical tool that will be used to measure the efficiency of estimators. Thus,

$$\text{PRE} = \frac{Var\,(\bar{y})}{Var\,(\bar{y}_*) \text{ or } MSE(\bar{y}_*)}\ X\ 100$$

for $*$=1,2,3,4,5,6,7,8,9,10 and $\bar{y}_1 = \bar{y}$, $\bar{y}_2 = \bar{y}_R$,$\bar{y}_3 = \bar{y}_P$, $\bar{y}_4 = \bar{y}_{ER}$,$\bar{y}_5 = \bar{y}_{EP}$, $\bar{y}_6 = \bar{y}_{lr}$,

$\bar{y}_7 = \bar{y}_{RC}$, $\bar{y}_8 = \bar{y}_{PC}$, $\bar{y}_9 = \bar{y}_{lrC}$, $\bar{y}_{10} = \bar{y}_{ERC}$

Table 1 shows the data that is used to assess the efficiency of the estimators discuss above.

Table 1: Data sets for the Empirical Study

Parameter	Population I	Population II	Population III	Population IV
N	27	34	49	36
n	12	12	12	12
$\bar{Y}$	11.25185	199.441	127.7959	14.77778
$\bar{X}$	10.41111	208.882	103.1429	2.798333
y_{max}	14.8	634	634	33
y_{min}	7.9	6	46	6
x_{max}	14.5	564	507	3.82
x_{min}	6.5	5	2	1.81
S_y	2.025586	150.215	123.1212	6.1788
S_x	2.220586	150.506	104.4051	0.5919
S_{yx}	4.454	22158.05	12619.78	−2.477
ρ_{yx}	0.990	0.980	0.98	−0.6772

Source: Khan and Shabbir (2013)

Table 2 below is the population description of the data of table 1, it states the study variable and the auxiliary variable

Table 2: Population description

Variable	Population I	Population II	Population III	Population IV
y	Milk yield in kg after new food	Weekly time (hours) spent in nonacademic activities	Area under wheat crop in 1964	Population size in 1930 (in 1000)
x	Yield in kg Before new yield	Overall grade point average (4.0 bases).	Area under wheat crop in 1963.	Population size in 1920 (in 1000).

The efficiency of the proposed estimators and its contemporary is showed in table 3 below:

Table 3: Percent elative efficiency of different estimators with respect to mean per

unit estimator

	POPULATION I		POPULATION II		POPULATION III		POPULATION IV	
ESTIMATOR	MSE	PRE	MSE	PRE	MSE	PRE	MSE	PRE
$\bar{y}$	0.189956	**100.00**	1216.716	**100.00**	953.872	**100.00**	2.12098	**100.00**
$\bar{y}_R$	0.010895	**1743.56**	48.6438	**2501.28**	39.0462	**2442.93**	4.11721	**51.5149**
$\bar{y}_P$	0.902317	**21.0521**	4611.82	**26.3825**	3974.67	**23.9988**	1.21035	**175.236**
$\bar{y}_{ER}$	0.033763	**562.615**	354.300	**343.414**	233.212	**409.014**	2.98339	**71.0928**
$\bar{y}_{EP}$	0.479474	**39.6176**	2635.89	**46.1596**	2201.02	**43.3376**	1.52996	**138.629**
$\bar{y}_{lr}$	0.003780	**5025.13**	48.1819	**2525.25**	37.7733	**2525.25**	1.14830	**184.706**
$\bar{y}_{RC}$	0.008180	**2322.06**	41.3840	**2940.07**	38.1144	**2502.66**	3.90413	**54.3265**
$\bar{y}_{Pc}$	0.899603	**21.1156**	4604.56	**26.4241**	3973.74	**24.0044**	0.997275	**212.677**
$\bar{y}_{lrC}$	0.003686	**5152.93**	42.7899	**2843.46**	37.7607	**2526.09**	1.01845	**208.255**
$\bar{y}_{ERC}$	0.027851	**682.052**	247.751	**491.105**	183.589	**519.569**	2.60992	**81.2659**

The analysis reveals a significant improvement in the precision of estimators that incorporate a correction factor for outliers, compared to their standard counterparts that do not account for such adjustments.

From table 3, in the first population, the estimators that hat apply an outlier correction factor $\bar{y}_{RC}$, $\bar{y}_{Pc}$, $\bar{y}_{lrC}$, $\bar{y}_{ERC}$ demonstrated it efficiency over the conventional estimators $\bar{y}_R$,$\bar{y}_P$, $\bar{y}_{lr}$, $\bar{y}_{ER}$ that do not incorporate such adjustments respectively. Also, in population I, II and III estimators $\bar{y}_{RC}$ and $\bar{y}_{ERC}$ performed better than $\bar{y}_{Pc}$, while in population IV $\bar{y}_{Pc}$ established it superiority over others estimators. But it is obvious that estimator $\bar{y}_{lrC}$ adapted well in all the four populations considered in this study.

Conclusions and Recommendations

In this study a generalized estimator under maximum and minimum values using auxiliary variable was developed that yielded the mean square error of the conventional estimators at different values of the constant ranges from -1 to +1. From the analysis, it can be observed that the ratio and exponential ratio estimator performed better when there is positive correlation. The performance of the generalized estimator depends on the choice of the values for the constant. The values of the constant should be carefully selected based on the specific context and the type of estimator required.

Thus, the proposed estimators may be preferred over the existing estimators for the use of practical applications, because it is versatile and encompasses various known estimators within its formulation by appropriately adjusting the constant. This flexibility allows it to adapt to different estimation scenarios.

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