

Review Form 1.6

| | |
|--------------------------|---|
| Journal Name: | Asian Journal of Research in Computer Science |
| Manuscript Number: | Ms_AJRCOS_92445 |
| Title of the Manuscript: | Research Status of Robot Grab Detection Based on Vision |
| Type of the Article | |

General guideline for Peer Review process:

This journal's peer review policy states that **NO** manuscript should be rejected only on the basis of '**lack of Novelty**', provided the manuscript is scientifically robust and technically sound. To know the complete guideline for Peer Review process, reviewers are requested to visit this link:

(<https://www.journalajrcos.com/index.php/AJRCOS/editorial-policy>)

PART 1: Review Comments

| | Reviewer's comment | Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here) |
|-------------------------------------|--|---|
| Compulsory REVISION comments | There are minor grammatical and typographical errors, please fix them for all pages (see page 1,2) | |
| Minor REVISION comments | Limitations and further study sections must be added | |
| Optional/General comments | Overall interesting article | |

PART 2:

| | Reviewer's comment | Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here) |
|--|---|---|
| Are there ethical issues in this manuscript? | (If yes, Kindly please write down the ethical issues here in details) | |

Reviewer Details:

| | |
|----------------------------------|----------------|
| Name: | Farhang Salehi |
| Department, University & Country | Iran |