

## Review Form 1.6

Journal Name:	Asian Journal of Research in Computer Science
Manuscript Number:	Ms_AJRCOS_92445
Title of the Manuscript:	Research Status of Robot Grab Detection Based on Vision
Type of the Article	Theoretical research

### General guideline for Peer Review process:

This journal's peer review policy states that **NO** manuscript should be rejected only on the basis of '**lack of Novelty**', provided the manuscript is scientifically robust and technically sound. To know the complete guideline for Peer Review process, reviewers are requested to visit this link:

(<https://www.journalajrcos.com/index.php/AJRCOS/editorial-policy> )

### PART 1: Review Comments

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
<b>Compulsory</b> REVISION comments	In general, the paper has well written and structured.	
<b>Minor</b> REVISION comments	In summary please write the comparison between 2D planar grasping and 6-DOF spatial grasping in a table showing the drawback and weakness for each.	
<b>Optional/General</b> comments	The author highlighted the comparison between 2D planar grasping and 6-DOF spatial grasping and prefer if could be summarised in a table.	

### PART 2:

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
Are there ethical issues in this manuscript?	(If yes, Kindly please write down the ethical issues here in details)	

### Reviewer Details:

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