

Review Form 1.6

Journal Name:	Journal of Advances in Medicine and Medical Research
Manuscript Number:	Ms_JAMMR_94233
Title of the Manuscript:	HANDLINK: A Dexterous Robotic Hand Exoskeleton controlled by Motor Imagery (MI) to Assist Individuals with Upper Body Paralysis
Type of the Article	Original Research Article

General guideline for Peer Review process:

This journal's peer review policy states that **NO** manuscript should be rejected only on the basis of '**lack of Novelty**', provided the manuscript is scientifically robust and technically sound. To know the complete guideline for Peer Review process, reviewers are requested to visit this link:

(<https://www.journaljammr.com/index.php/JAMMR/editorial-policy>)

PART 1: Review Comments

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
Compulsory REVISION comments	<p>ABSTRACT: You do not use complete words in certain parts, so I suggest you include the complete description of the terms that appear abbreviated, as it is also the first appearance in the manuscript, such as EEG. In addition, it must include the statistical test used to determine that there was no difference between the experimental group and the control group.</p> <p>DISCUSSION At the beginning of the text of the discussion, the information given in the introduction is reiterated and an introduction to the discussion is made again, and the interpretations and comments of the authors are based only on the data published in the study, for which reason I suggest increasing the comparison to other similar studies and adequately commenting and reflecting on the main limitations of the study, confirming the absence of bias, in addition to trying to coherently justify the internal and external validity of the study.</p>	
Minor REVISION comments	<p>TITLE: The title is too long and even redundant, in addition to the fact that its use can be extended beyond what is specified in the title, so I suggest it be abbreviated, it could be simply: HANDLINK: A robotic hand exoskeleton controlled by motor images (MI).</p> <p>INTRODUCTION I suggest including expected limitations.</p>	
Optional/General comments		

PART 2:

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
Are there ethical issues in this manuscript?	(If yes, Kindly please write down the ethical issues here in details)	

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Reviewer Details:

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