

## Review Form 1.6

Journal Name:	<b>Journal of Advances in Medicine and Medical Research</b>
Manuscript Number:	<b>Ms_JAMMR_94233</b>
Title of the Manuscript:	<b>HANLINK: A Dexterous Robotic Hand Exoskeleton controlled by Motor Imagery (MI) to Assist Individuals with Upper Body Paralysis</b>
Type of the Article	

### **General guideline for Peer Review process:**

This journal's peer review policy states that **NO** manuscript should be rejected only on the basis of '**lack of Novelty**', provided the manuscript is scientifically robust and technically sound. To know the complete guideline for Peer Review process, reviewers are requested to visit this link:

(<https://www.journaljammr.com/index.php/JAMMR/editorial-policy> )

### **PART 1: Review Comments**

	<b>Reviewer's comment</b>	<b>Author's comment</b> (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
<b>Compulsory</b> REVISION comments	<b>NO</b>	
<b>Minor</b> REVISION comments	<b>This article is novel but needs some grammar corrections and punctuation</b>  All the suggestions are made in the manuscript file and can be checked by the author by opening the manuscript file in MS word and clicking on review and then suggestions can be accepted or rejected by the author.	
<b>Optional/General</b> comments	<b>NO</b>	

### **PART 2:**

	<b>Reviewer's comment</b>	<b>Author's comment</b> (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
<b>Are there ethical issues in this manuscript?</b>	<i>(If yes, Kindly please write down the ethical issues here in details)</i>	

### **Reviewer Details:**

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